



## **Technical specifications**

1.	Type of crane in	Gantry double-girder container crane
	structure	Semi-gantry container crane
	Crane group	General purpose gantry container crane
		Assemble gantry crane
		Gantry crane with magnets
		Gantry crane with magnets and grab
2.		Gantry crane with grab
		Container gantry crane
		Special gantry crane for hydroelectric power plants and hydraulic structures
		Special gantry crane for nuclear facilities
		Special gantry crane



3. Using of crane and crane's mechanisms 3.1 Type of drive **Electrical** 3.2 Estimated qualification groups of the crane and its mechanisms according to ISO 4301-1 3.2.1 Crane in general (A3-A8) Α 3.2.2 M Main crane hoist in general (M1-M8) 3.2.3 Auxiliary crane hoist (M1-M8) M 3.2.4 Trolley travel mechanism (M1-M8) М Trolley rotating mechanism/load-handling device (jaws, hook 3.2.5 M etc.) (M1-M8) 3.2.6 М Crane travel mechanism (M1-M8) 3.2.7 Other groups: М Lifting capacity, t with removable load-handling device with stationary load-handling device (hook, etc.) of ropes 3.3 of trolleys of spreader other: 3.4 Crane span, m 3.5 Lifting height, m 3.6 L2 Work radius on consoles (L≥0), m L1 Offered by the 3.7 Crane size along its way (with uncompressed buffers), m manufacturer Quantity of cargo trolleys and lifting mechanisms with one trolley and one lifting mechanism 3.8 with one trolley and several lifting mechanisms with two trolleys and any number of lifting mechanisms with one or two trolleys and a hoist Load-handling device rotation: not provided together with a load-handling device 3.9 rotating mechanism together with rotating trolley



3.10	Rotating angle limitations: hook/trolley/traverse/spreader/other:					
3.10.1						
3.11 M	echanisms speed					
3.11.1	Main crane hoist, m/sec (m/min)	V=				
3.11.2	Auxiliary crane hoist, m/sec (m/min)	V=				
3.11.3	Trolley travel mechanism, m/sec (m/min)	V=				
3.11.4	Trolley/load-handling device (hook, traverse, spreader etc.) rotating mechanism, rpm	V=				
3.11.5	Crane travel, m/sec (m/min)	V=				
3.11.6	Other:	V=				
3.12 H	eight from the rail head level					
3.12.1	Of load lifting, m					
3.12.2	Of load lowering, m					
3.13	Distance from rail head level up to lower truss elements (for indoor cranes and cranes located under the roof), m					
3.14	Distance from rail head level axis up to pillars and other crane travelling way elements, m					
3.15	Crane rail type					
3.16	Permissible wheel load, kN(t)					
4 Operating conditions						
4.1	Operating temperature range, °C	from	up to			
4.2	Placement category: (outdoor – «1», under the roof – «2», not heating zone – «3», heating zone – «4», high humidity zone – «5»)					
4.3 Wi	nd load					
4.3.1	Maximum wind speed in crane operation mode, m/sec	V=				
4.J. I	out of use, m/sec	V=				



4.4	Seismic resistance, (Richter scale)					up to		
4.5 Dustiness level:								
4.5.1	Type of the dust (mat	terial)						
4.5.2	Density, mg/m <sup>3</sup>							
4.6 H	eatstroke possibilitie	es						
4.6.1	Source (no source/load/furnace etc.)							
4.6.2	Main impact on (suspension/traverse/bridge girder/trolley etc.)							
4.6.3	Temperature, °C				from	up to		
4.6.4	Duration, min				from	up to		
4.7	Other special conditions							
5 (	Crane purpose							
5.1.	Load handling: bulk load, specify:							
5.1.	general cargoes, specify:							
Execution of technological operations:								
	Warehouse maintenance		Freight transport loading					
5.2	Freight train loading		Furnace loading					
	Assembly operations Other:							
6 Load characteristics								
6.1.1	General cargo or load package of the 1 <sup>st</sup> type							
6.1.1.1	Maximum weight on a load-handling device, t							
6.1.1.2	Maximum dimensions, mm	length	width (diameter) height (depth)			height (depth)		



no yes 6.1.1.3 Availability of special slinging points: 6.1.1.4 Load temperature, °C from up to 6.1.1.5 Other: General cargo or load package of the 2<sup>nd</sup> type 6.1.2 6.1.2.1 Maximum weight on a load-handling device, t Maximum 6.1.2.2 dimensions, mm length width (diameter) height (depth) yes 6.1.2.3 Availability of special slinging points: 6.1.2.4 Load temperature, °C from up to 6.1.2.5 Other: 6.2.1 Bulk load of the 1<sup>st</sup> type 6.2.1.1 Name of material 6.2.1.2 Load conditions (normal, frozen, caked, in pieces etc.) Maximum 6.2.1.3 Density, t/m3 temperature, °C 6.2.1.4 Other: Bulk load of the 2<sup>nd</sup> type 6.2.2 6.2.2.1 Name of material 6.2.2.2 Load conditions (normal, frozen, caked, in pieces etc.) Maximum 6.2.2.3 Density, t/m<sup>3</sup> temperature, °C 6.2.2.4 Other: Load handling device type and characteristics 7 one-horn hook double-horn hook Main hook I one-horn hook double-horn hook Main hook II 7.1 Hooks one-horn hook double-horn hook Auxiliary hook I double-horn hook one-horn hook Auxiliary hook II



Characteristics are offered by the manufacturer Double-rope Four-rope Mounted Permanent on a hook Manual Electric Hydraulic drive drive drive Foreign drive Russian drive Drive trade mark 7.2 Grab Intended for Not intended for unloading wagons unloading wagons Double jaw Multi jaw Longitudinal Lateral Orientation regarding crane ropes opening opening (for double-jaw four-rope grab) Volume capacity, m<sup>3</sup> Calculated by the manufacturer Other: Characteristics are offered by the manufacturer Rectangular Round Special profile shape profile shape profile shape Load capacity, t Quantity, pcs. 7.3 Magnet Foreign drive Russian drive Drive trade mark Type Load temperature, °C from up to Other: Characteristics are offered by the manufacturer Mounted Permanent on a hook 7.4 **Spreader** Foreign made Russian made Spreader trade mark Manual Electric Hydraulic drive drive drive



		Container standard siz	œ.				
		Replaceable by standard size	Sliding				
		Location					
		Other:					
		Characteristics are offered by the manufacturer					
		Permanent	Permanent				
		Vacuum traverse	Hook traverse		Magnet traverse		
		Located along bridge girder	Located acr		Need for rotation		
		Complete set of trave			Totalion		
		7.5.1 with hooks	Quantity		Lifting capacity. t		
		7.5.2 with magnets					
7.5	Traverse		Separate crane mechanism				
7.5	iraverse	7.5.3 with claws	Electric drive				
			Hydraulic d	Hydraulic drive			
			Lifting capa	city,t			
		7.5.4 with slings	Sling's leng	th, mm			
		7.3.4 with sings	Sling type				
			Quantity, pcs.				
		7.5.5 Other					
		Characteristics are offe	ered by the mai				
		Permanent	Permanent		Mounted on a hook		
	Differen	Foreign made	Foreign made		Russian made		
7.6	Pliers	Trade mark	Trade mark				
		Manual drive	Electric drive		Hydraulic drive		
		Located along the crane runway			Located across the crane runway		



	С	Other						
7.7		Characteristics are offered by the manufacturer						
7.7		ouble hook uspension			our-hook suspension			
7.8	Automatic capture	<u> </u>			·			
7.9	Other load-handling device							
8 Con	structional requireme	ents						
8.1	Alignment restrictions for working movements of mechanisms							
8.2	Need for synchronization speeds when working together			yes			no	
				Trolley				
8.3	Crane's current supply type			Cable	Re	eel	Tracking	
8.4	Control cabin			Mobile	Stationary		nary	
8.5	Control cabin location							
8.6	Type of the control system			Frequency				
8.7	Complete set of the cor							
9 Add	itional requirements							
9.1	Complete set of the crane							
No.	Name	Unit Qty.			Manufa	cturer		
1								
2								
3								
4								
9.2	Technical documentation, provided by the Customer							
Dimensional drawing			Other:					
9.3	Painting							
9.3.1	Enamel							



9.3.2	Enamel color: yellow /					
9.4	Additional requirements of the Customer					
10 Cus	10 Customer information					
10.1	Company name					
10.2	Address					
10.3	Contact person					
10.4	Phone					
10.5	E-mail					

## Thank you for the provided information!

Please, send us this form to our e-mail address: info@tehnoros.com